Product data sheet

Specifications

variable speed drive, Altivar Process ATV600, ATV630, 90kW, 125hp, 500 to 690V, IP00

ATV630D90Y6

Main

Range of product	Altivar Process ATV600
Product specific application	Process and utilities
Product or component type	Variable speed drive
Variant	Standard version
Device short name	ATV630
Mounting mode	Wall mount
Communication port protocol	Modbus TCP Modbus serial Ethernet
[Us] rated supply voltage	500...690 V - 15...10 %
[Us] rated supply voltage	500...690 V
Relative symmetric mains voltage tolerance	10 %
Relative symmetric network frequency tolerance	5 %
nominal output current	108.0 A
IP degree of protection	IP21
Product destination	Asynchronous motors Synchronous motors
EMC filter	Integrated with 25 m conforming to IEC 61800-3 category C3
IP degree of protection	IP00 conforming to IEC 61800-5-1 IP00 conforming to IEC 60529 IP20 (with kit VW3A9706) conforming to IEC 61800-5-1 IP20 (with kit VW3A9706) conforming to IEC 60529
Type of cooling	Forced convection
Supply frequency	50...60 Hz - 5...5 %
Motor power kW	75 kW at 500 V (normal duty) 55 kW at 500 V (heavy duty) 90 kW at 690 V (normal duty) 75 kW at 690 V (heavy duty)
Motor power hp	100 hp at 500 V normal duty 75 hp at 500 V heavy duty 125 hp at 690 V normal duty 100 hp at 690 V heavy duty
Line current	108.3 A at 500 V (normal duty) 99.4 A at 690 V (normal duty) 82.7 A at 500 V (heavy duty) 87.7 A at 690 V (heavy duty)
Continuous output current	83 A at 2.5 kHz for heavy duty 108 A at 2.5 kHz for normal duty

Speed drive output frequency	0.1…500 Hz
Safety function	STO (safe torque off) SIL 3
Option card	Slot A: communication module, Profibus DP V1 Slot A: communication module, PROFINET Slot A: communication module, DeviceNet Slot A: communication module, Modbus TCP/EtherNet/IP Slot A: communication module, CANopen daisy chain RJ45 Slot A: communication module, CANopen SUB-D 9 Slot A: communication module, CANopen screw terminals Slot A/slot B: digital and analog I/O extension module Slot A/slot B: output relay extension module Slot A: communication module, Ethernet IP/Modbus TCP/MD-Link Communication module, BACnet MS/TP Communication module, Ethernet Powerlink

Complementary

Discrete input number	8
Discrete input type	DI7, DI8 programmable as pulse input: 0…30 kHz, 24 V DC (<= 30 V)
Discrete input logic	16 preset speeds
Discrete output number	0
Discrete output type	Relay outputs R1A, R1B, R1C 250 V AC 3000 mA Relay outputs R1A, R1B, R1C 30 V DC 3000 mA Relay outputs R2A, R2C 250 V AC 5000 mA Relay outputs R2A, R2C 30 V DC 5000 mA Relay outputs R3A, R3C 250 V AC 5000 mA Relay outputs R3A, R3C 30 V DC 5000 mA
Analogue input number	3
Analogue input type	AI1, AI2, AI3 software-configurable voltage: 0...10 V DC, impedance: 31.5 kOhm, resolution 12 bits AI1, AI2, AI3 software-configurable current: 0...20 mA, impedance: 250 Ohm, resolution 12 bits AI2 voltage analog input: - 10...10 V DC, impedance: 31.5 kOhm, resolution 12 bits
Analogue output number	2
Analogue output type	Software-configurable voltage AQ1, AQ2: 0...10 V DC impedance 470 Ohm, resolution 10 bits Software-configurable current AQ1, AQ2: 0...20 mA, resolution 10 bits Software-configurable current DQ-, DQ+: 30 V DC Software-configurable current DQ-, DQ+: 100 mA
Relay output number	3
Relay output type	Configurable relay logic R1: fault relay NO/NC electrical durability 100000 cycles Configurable relay logic R2: sequence relay NO electrical durability 100000 cycles Configurable relay logic R3: sequence relay NO electrical durability 100000 cycles
Maximum switching current	Relay output R1, R2, R3 on resistive load, cos phi = 1: 3 A at 250 V AC Relay output R1, R2, R3 on resistive load, cos phi = 1: 3 A at 30 V DC Relay output R1, R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R1, R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC
Minimum switching current	Relay output R1, R2, R3: 5 mA at 24 V DC
Network number of phases	3 phases
Physical interface	Ethernet 2-wire RS 485
Method of access	Slave Modbus TCP
Transmission rate	10, 100 Mbits 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps
Transmission frame	RTU
Output voltage	<= power supply voltage

Permissible temporary current boost	1.1 x In during 60 s (normal duty) 1.5 x In during 60 s (heavy duty)
Data format	8 bits, configurable odd, even or no parity
Type of polarization	No impedance
Frequency resolution	Display unit: 0.1 Hz Analog input: 0.012/50 Hz
Electrical connection	Control: removable screw terminals 0.5...1.5 mm²/AWG 20...AWG 16 Motor: screw terminal 50 mm²/AWG 1 Line side: screw terminal 50 mm²/AWG 1
Connector type	RJ45 (on the remote graphic terminal) for Ethernet/Modbus TCP RJ45 (on the remote graphic terminal) for Modbus serial
Exchange mode	Half duplex, full duplex, autonegotiation Ethernet/Modbus TCP
Number of addresses	1…247 for Modbus serial
Supply	External supply for digital inputs: 24 V DC (19…30 V), <1.25 mA, protection type: overload and short-circuit protection Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC +/- 5 %, <10 mA, protection type: overload and short-circuit protection Internal supply for digital inputs and STO: 24 V DC (21…27 V), <200 mA, protection type: overload and short-circuit protection
Local signalling	3 LEDs for local diagnostic 3 LEDs (dual colour) for embedded communication status 4 LEDs (dual colour) for communication module status 1 LED (red) for presence of voltage
Input compatibility	DI1...DI6: discrete input level 1 PLC conforming to IEC 61131-2 DI5, DI6: discrete input level 1 PLC conforming to IEC 65A-68 STOA, STOB: discrete input level 1 PLC conforming to IEC 61131-2
Discrete input logic	Positive logic (source) (DI1...DI8), < 5 V (state 0), > 11 V (state 1) Negative logic (sink) (DI1...DI8), > 16 V (state 0), < 10 V (state 1)
Sampling duration	2 ms +/- 0.5 ms (DI1...DI4) - discrete input 5 ms +/- 1 ms (DI5, DI6) - discrete input 5 ms +/- 0.1 ms (AI1, AI2, AI3) - analog input 10 ms +/- 1 ms (AO1) - analog output
Accuracy	+/- 0.6 % AI1, AI2, AI3 for a temperature variation 60 °C analog input +/- 1 % AO1, AO2 for a temperature variation 60 °C analog output
Linearity error	AI1, AI2, AI3: +/- 0.15 % of maximum value for analog input AO1, AO2: +/- 0.2 % for analog output
Refresh time	Relay output (R1, R2, R3): 5 ms (+/- 0.5 ms)
Isolation	Between power and control terminals
Enclosure mounting	Wall mounted
4 quadrant operation possible	False
Asynchronous motor control profile	Constant torque standard Optimized torque mode Variable torque standard
Synchronous motor control profile	Permanent magnet motor Synchronous reluctance motor
Maximum output frequency	500 kHz
Acceleration and deceleration ramps	Linear adjustable separately from 0.01...9999 s S, U or customized
Motor slip compensation	Adjustable Can be suppressed Not available in permanent magnet motor law Automatic whatever the load
Switching frequency	1...4.9 kHz adjustable 2.5...4.9 kHz with derating factor
Nominal switching frequency	2.5 kHz

Braking to standstill	By DC injection
Brake chopper integrated	False
Maximum input current	108.3 A
Maximum output voltage	690.0 V
Apparent power	118.8 kVA at 690 V (normal duty) 104.8 kVA at 690 V (heavy duty)
Maximum transient current	124.5 A during 60 s (heavy duty) 118.8 A during 60 s (normal duty)
Network frequency	50...60 Hz
Prospective line Isc	70 kA
Base load current at high overload	83.0 A
Base load current at low overload	108.0 A
Power dissipation in W	Natural convection: 320 W at 500 V, switching frequency 2.5 kHz Forced convection: 1433 W at 500 V, switching frequency 2.5 kHz
With safety function Safely Limited Speed (SLS)	False
With safety function Safe brake management (SBC/SBT)	False
With safety function Safe Operating Stop (SOS)	False
With safety function Safe Position (SP)	False
With safety function Safe programmable logic	False
With safety function Safe Speed Monitor (SSM)	False
With safety function Safe Stop 1 (SS1)	False
With sft fct Safe Stop 2 (SS2)	False
With safety function Safe torque off (STO)	True
With safety function Safely Limited Position (SLP)	False
With safety function Safe Direction (SDI)	False
Protection type	Thermal protection: motor Safe torque off: motor Motor phase break: motor Thermal protection: drive Safe torque off: drive Overheating: drive Overcurrent between output phases and earth: drive Overload of output voltage: drive Short-circuit protection: drive Motor phase break: drive Overvoltages on the DC bus: drive Line supply overvoltage: drive Line supply undervoltage: drive Line supply phase loss: drive Overspeed: drive Break on the control circuit: drive
Quantity per set	1
Width	331 mm
Height	630 mm
Depth	297 mm
Net weight	53 kg

Environment

Insulation resistance	> 1 MOhm 500 V DC for 1 minute to earth
Noise level	52 dB conforming to 86/188/EEC
Pollution degree	2 conforming to IEC 61800-5-1
Vibration resistance	1.5 mm peak to peak (f= 2…13 Hz) conforming to IEC 60068-2-6 1 gn (f= 13…200 Hz) conforming to IEC 60068-2-6
Shock resistance	15 gn for 11 ms conforming to IEC 60068-2-27
Relative humidity	5…95 % without condensation conforming to IEC 60068-2-3
Ambient air temperature for operation	-15…50 °C (without derating) 50…60 °C (with derating factor)
Operating altitude	<= 1000 m without derating 1000...4800 m with current derating 1 % per 100 m
Operating position	Vertical +/- 10 degree
Product certifications	CSA TÜV UL
Marking	CE
Standards	UL 508C IEC 61800-3 EN/IEC 61800-3 environment 2 category C3 IEC 61800-5-1 IEC 61000-3-12 IEC 60721-3 IEC 61508 IEC 13849-1
Maximum THDI	<48 % with external line choke conforming to IEC 61000-3-12
Electromagnetic compatibility	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6
Environmental class (during operation)	Class 3C3 according to IEC 60721-3-3 Class 3S3 according to IEC 60721-3-3
Maximum acceleration under shock impact (during operation)	150 m/s² at 11 ms
Maximum acceleration under vibrational stress (during operation)	10 m/s² at 13...200 Hz
Maximum deflection under vibratory load (during operation)	1.5 mm at 2...13 Hz
Permitted relative humidity (during operation)	Class 3K5 according to EN 60721-3
Volume of cooling air	406 m3/h
Overvoltage category	III
Regulation loop	Adjustable PID regulator
Noise level	56 dB
Pollution degree	2
Ambient air transport temperature	-40…70 °C
Ambient air temperature for storage	-40…70 °C

Packing Units

Unit Type of Package 1	PCE
Number of Units in Package 1	1

Package 1 Height	58.000 cm
Package 1 Width	43.500 cm
Package 1 Length	110.000 cm
Package 1 Weight	68.000 kg

Environmental Data

Schneider Electric aims to achieve Net Zero status by 2050 through supply chain partnerships, lower impact materials, and circularity via our ongoing “Use Better, Use Longer, Use Again” campaign to extend product lifetimes and recyclability.

Environmental Data explained >

How we assess product sustainability >

Environmental footprint

Total lifecycle Carbon footprint	23723
Environmental Disclosure	Product Environmental Profile

Use Better

Materials and Substances

Packaging made with recycled cardboard	Yes
Packaging without single use plastic	No
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope)
SCIP Number	94885478-b375-4334-93be-492cfc5a4813
REACh Regulation	REACh Declaration
California proposition 65	WARNING: This product can expose you to chemicals including: Lead and lead compounds, which is known to the State of California to cause cancer and birth defects or other reproductive harm. For more information go to www.P65Warnings.ca.gov

Energy efficiency

Product contributes to saved and avoided emissions	Yes

Use Again

Repack and remanufacture

End of life manual availability	End of Life Information
Take-back	No
WEEE Label	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins

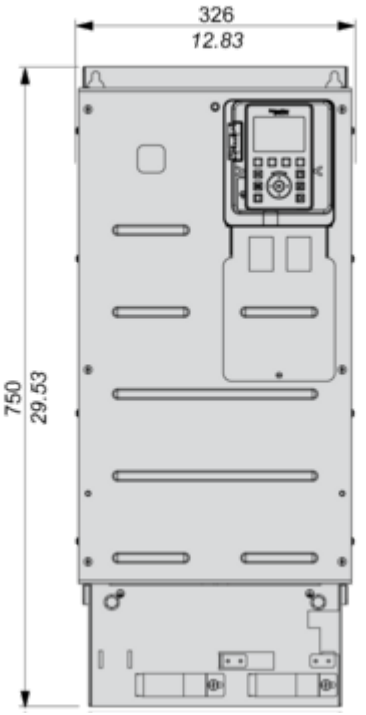
Dimensions Drawings

Dimensions

Drives without Top Cover

Front View with EMC Plate, Front, Left and Rear Views without EMC Plate

mm
in.



mm
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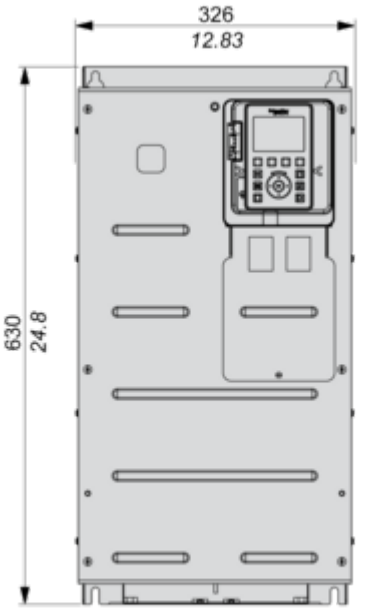

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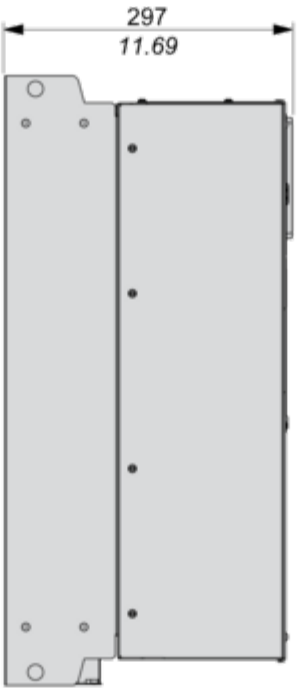

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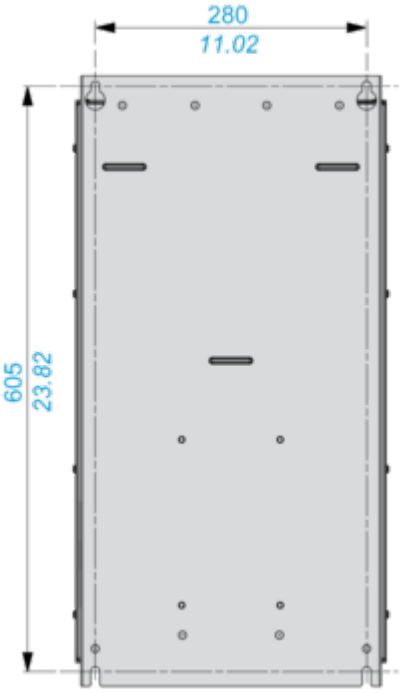
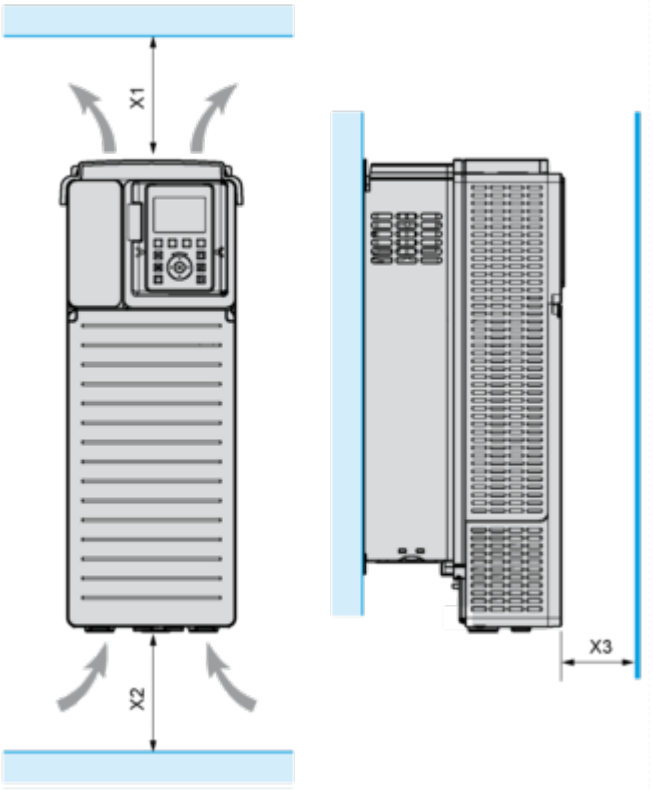


Mounting and Clearance

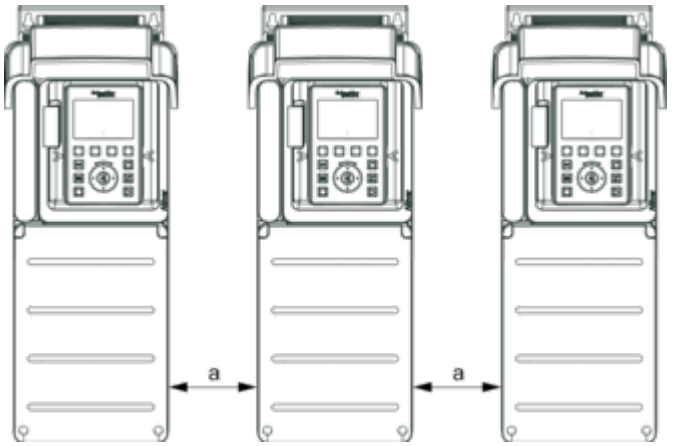
Clearances



X1	X2	X3
≥ 100 mm (3.94 in.)	≥ 100 mm (3.94 in.)	≥ 10 mm (0.39 in.)

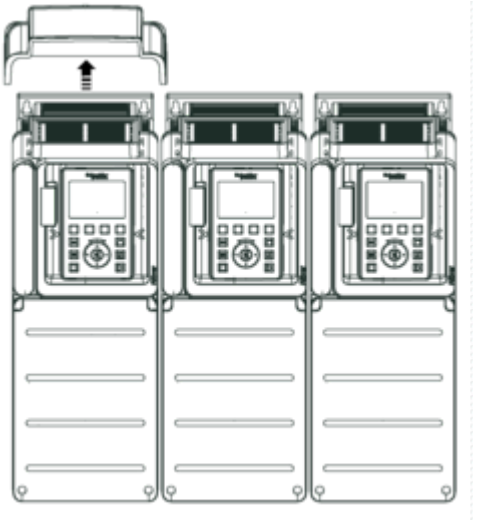
Mounting Types

Mounting Type A: Individual IP21

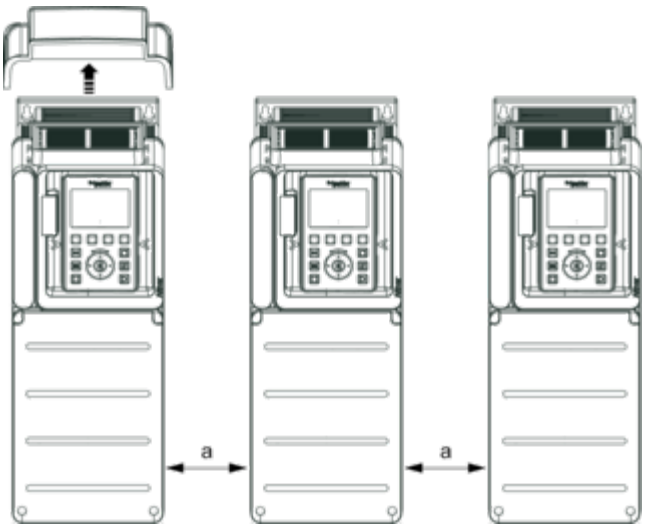


a ≥ 0

Mounting Type B: Side by Side IP20



Mounting Type C: Individual IP20

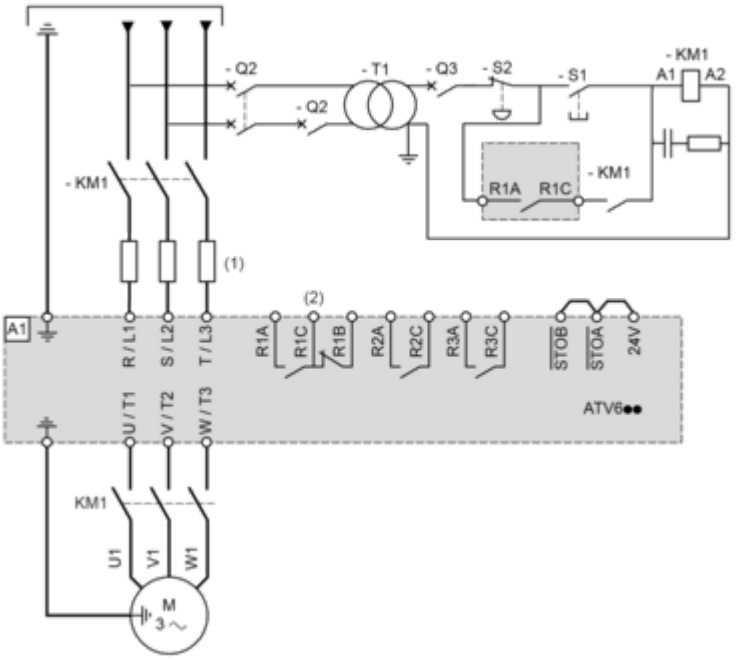


a ≥ 0

Connections and Schema

Three-Phase Power Supply with Upstream Breaking via Line Contactor

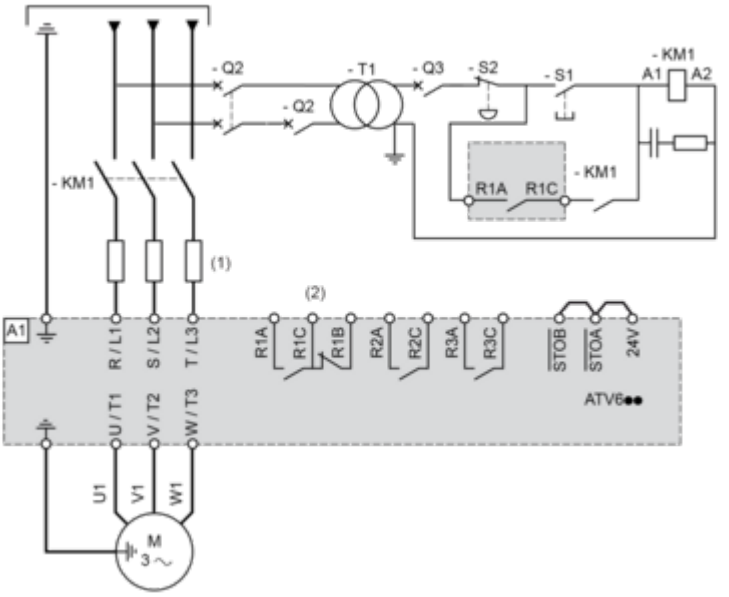
Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



(1) Line choke if used
(2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.
A1 : Drive
KM1 : Line Contactor
Q2, Q3 : Circuit breakers
S1, S2 : Pushbuttons
T1 : Transformer for control part

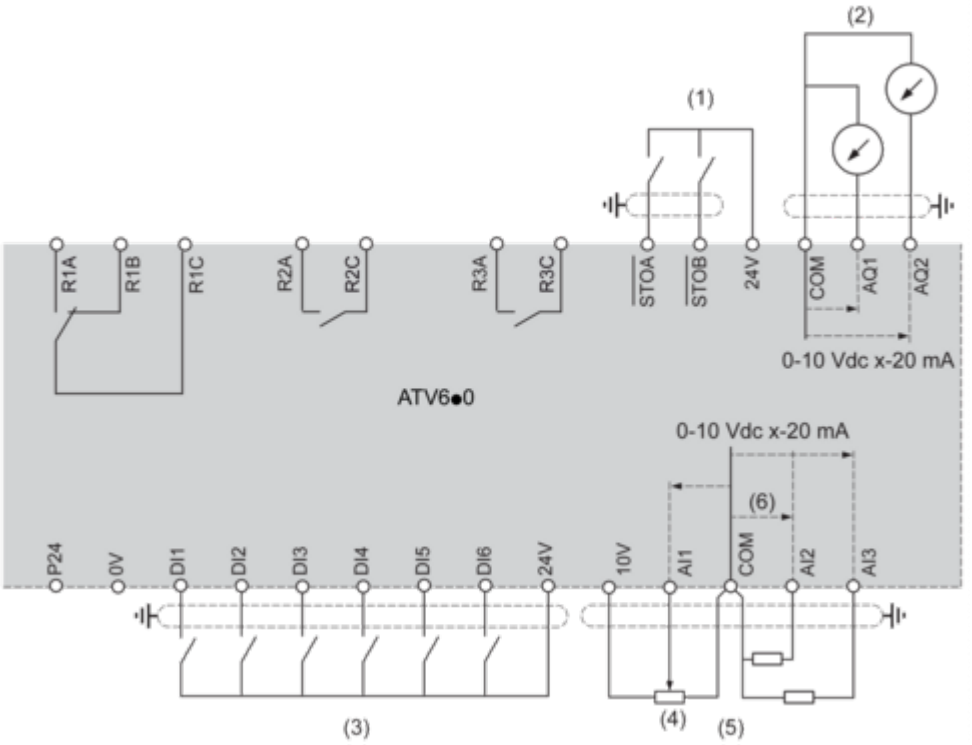
Three-Phase Power Supply with Downstream Breaking via Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



(1) Line choke if used
(2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.
A1 : Drive
KM1 : Contactor

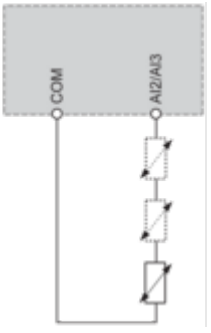
Control Block Wiring Diagram



(1) Safe Torque Off
(2) Analog Output
(3) Digital Input
(4) Reference potentiometer
(5) Analog Input
R1A, R1B, R1C : Fault relay
R2A, R2C : Sequence relay
R3A, R3C : Sequence relay

Sensor Connection

It is possible to connect either 1 or 3 sensors on terminals AI2 or AI3.

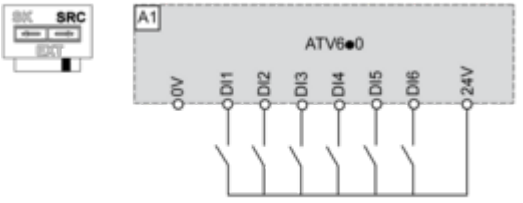


Sink / Source Switch Configuration

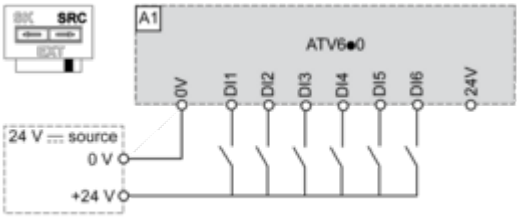
The switch is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

- Set the switch to Source (factory setting) if using PLC outputs with PNP transistors.
- Set the switch to Ext if using PLC outputs with NPN transistors.

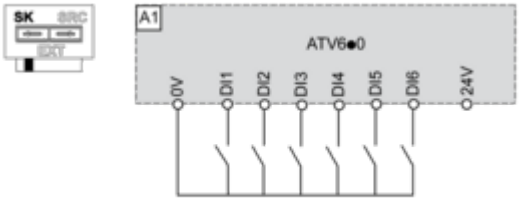
Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs



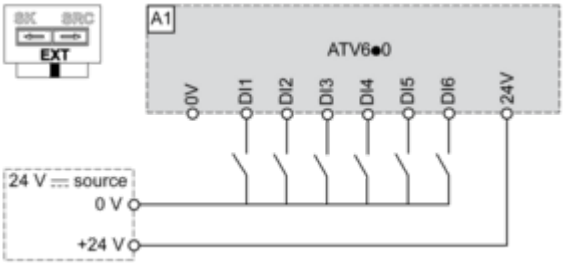
Switch Set to SRC (Source) Position and Use of an External Power Supply for the DIs



Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs

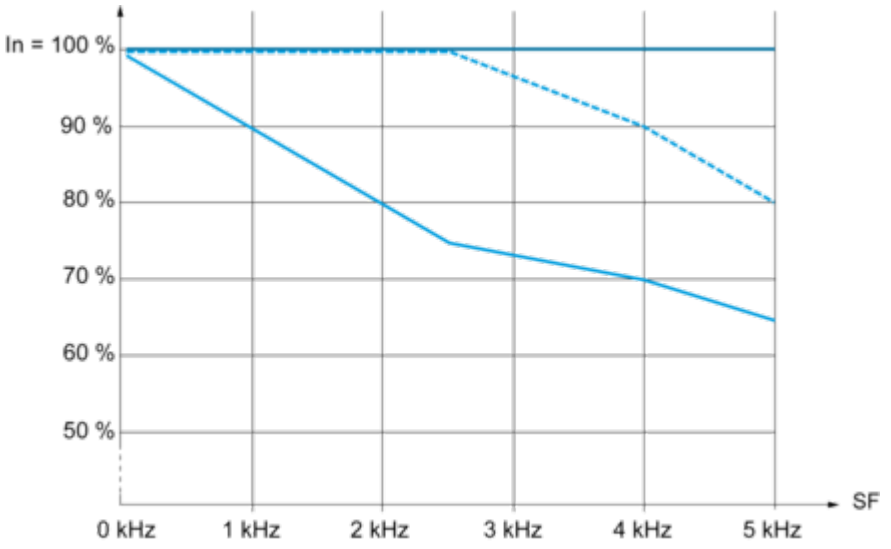


Switch Set to EXT Position Using an External Power Supply for the DIs



Performance Curves

Derating Curves

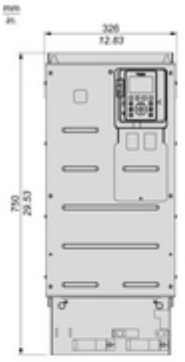


40 °C (104 °F) - Mounting type A, B and C
50 °C (122 °F) - Mounting type A, B and C
60 °C (140 °F) - Mounting type B and C
In : Nominal Drive Current
SF : Switching Frequency

Technical Illustration

Dimensions

Drives Without Top Cover, With EMC Plate



Drives Without Top Cover, Without EMC Plate